

Smart Aquarium



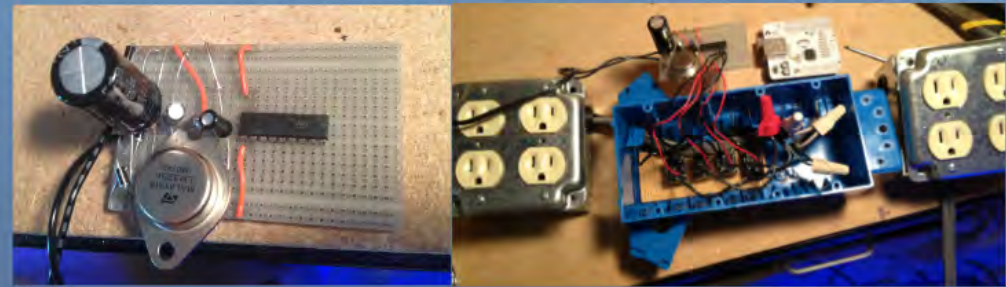
Smart Aquarium



Overview

Existing Components

- Arduino with Ethernet Shield
- External power supply
- Relays powered through ULN2803 drivers
- LED lighting system
- Servo motor feeding system
- Sump pump

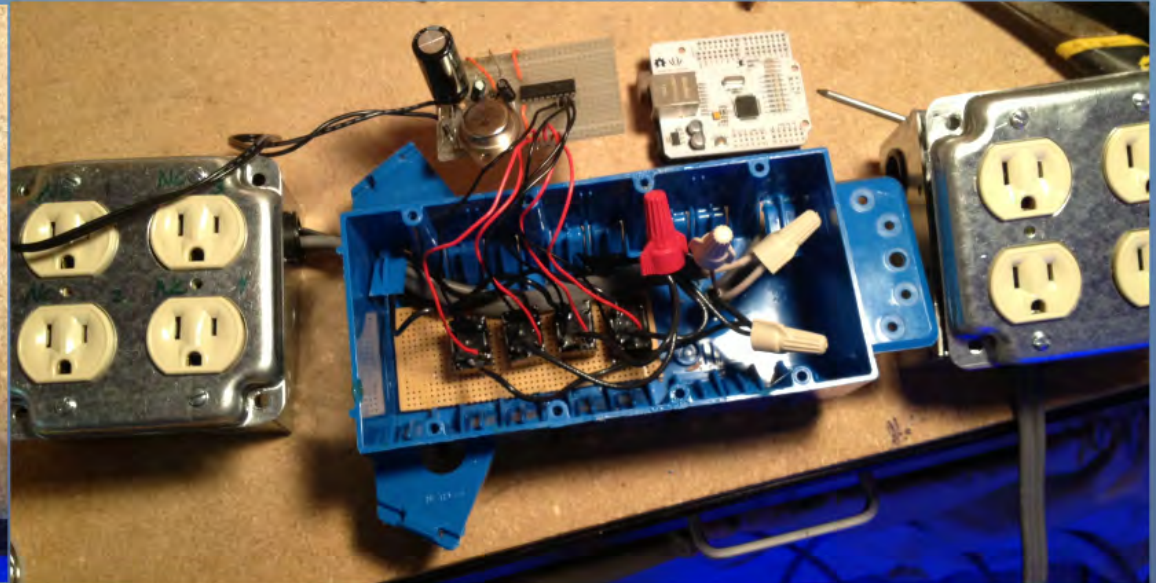
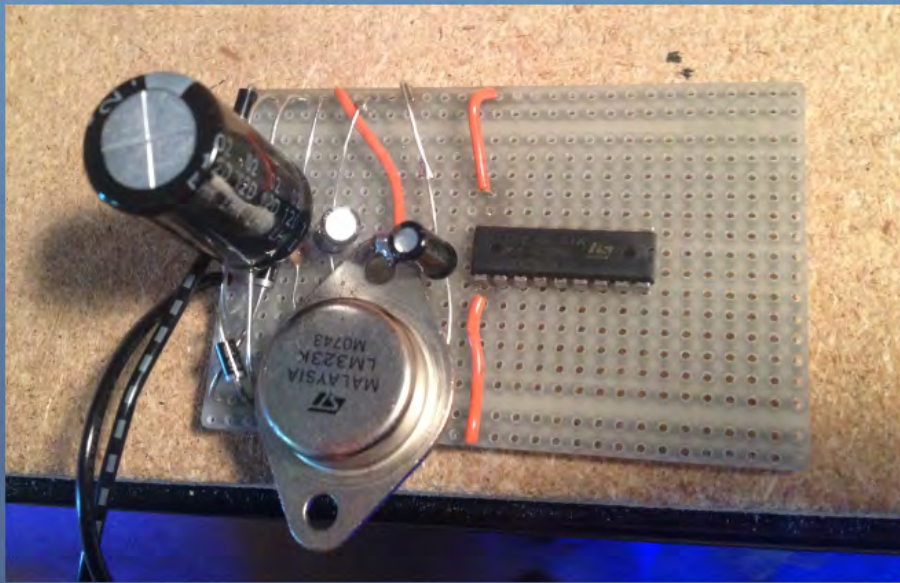


New features for EENG 383 Project

- Second Arduino
- LCD display screen with joystick button
- Infrared Distance Sensor



view



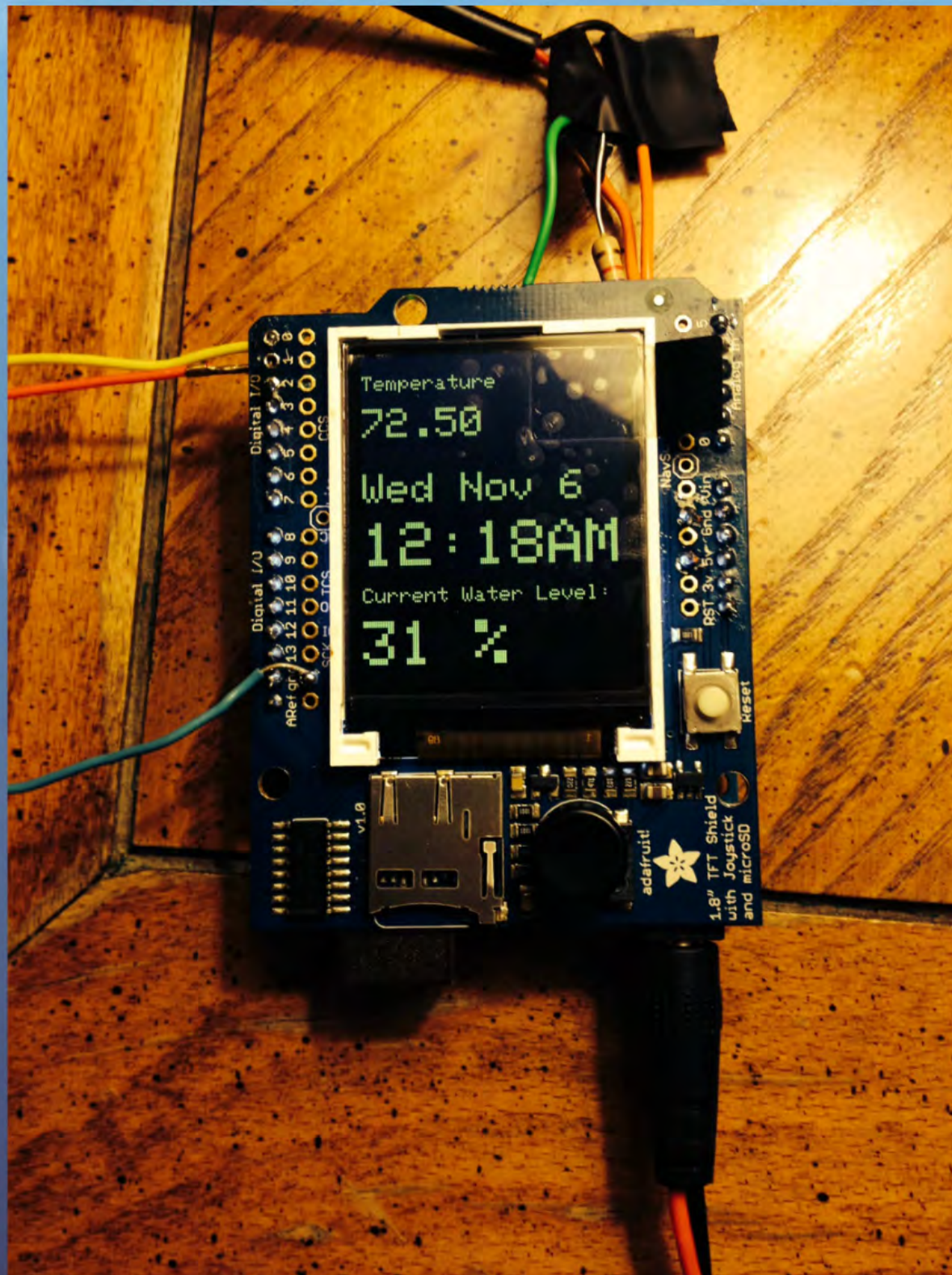
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New features for EENG 383 Project

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- Infrared Distance Sensor
- Waterproof Temperature IC





Communications

Temperature IC

- One Wire Communications Protocol
- Use Arduino library OneWire

IR distance sensor

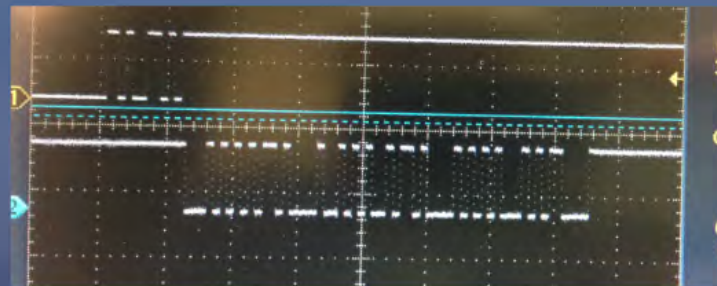
- Analog voltage reading

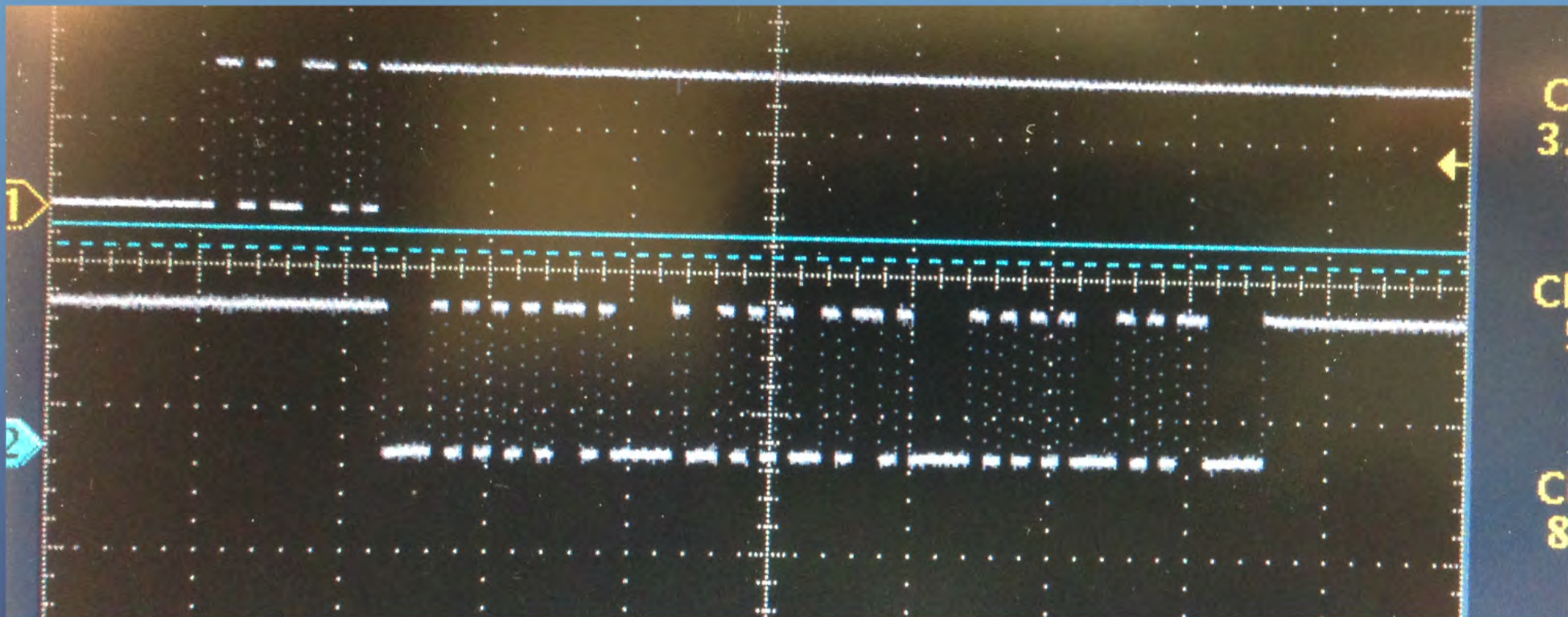
Joystick

- Voltage Divider for 5 separate signals using analog pin

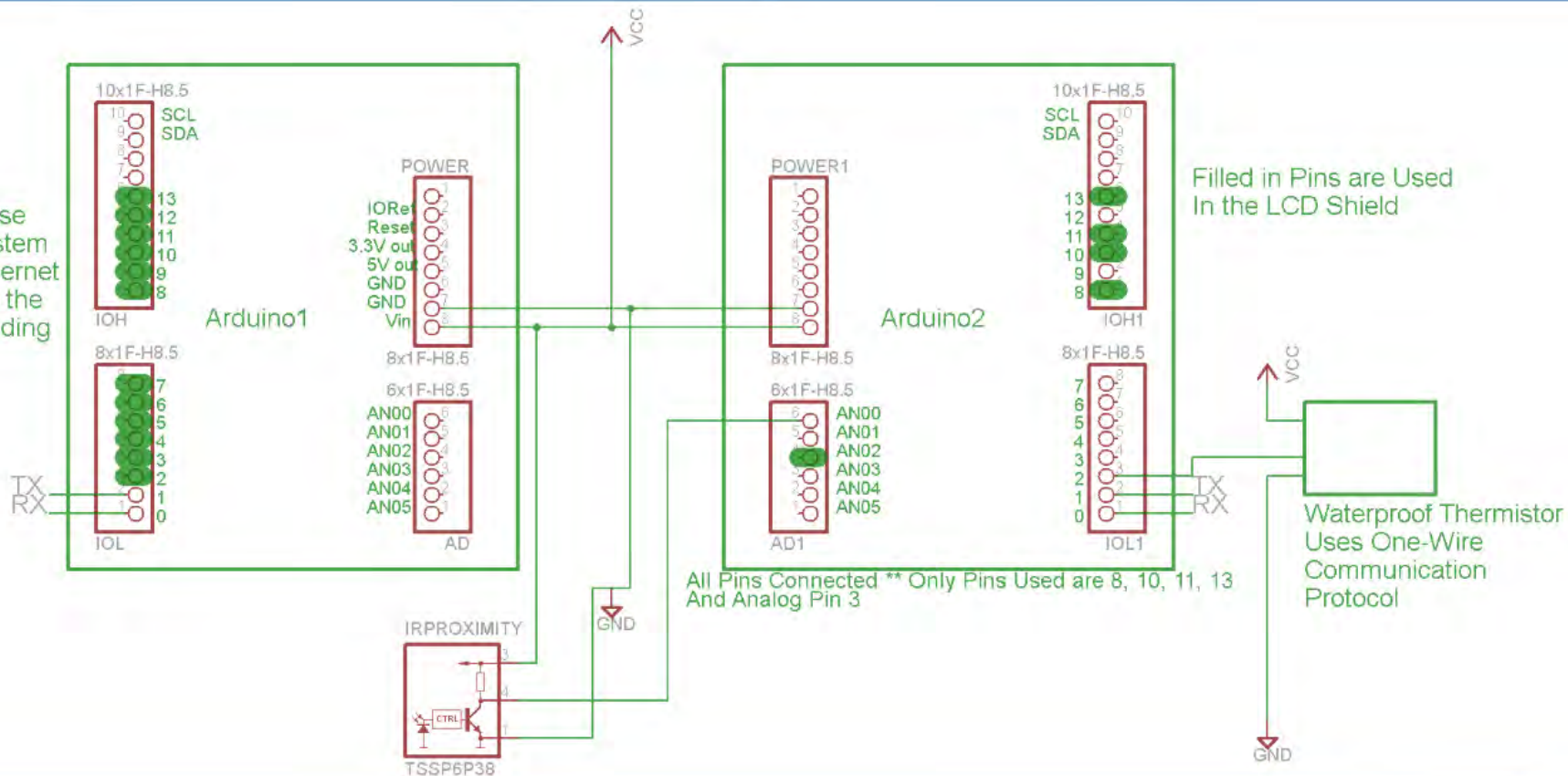
Arduinos

- Serial Communications (RS232)
- "Handshake" method





Filled in Pins Are Already In Use On the Currently Running System For Interconnection to the Ethernet Shield, And Power Outputs to the Controlled Components, Including One Servo Control Pin



Filled in Pins are Used In the LCD Shield

All Pins Connected ** Only Pins Used are 8, 10, 11, 13 And Analog Pin 3

Waterproof Thermistor Uses One-Wire Communication Protocol

Code Flow

Overview

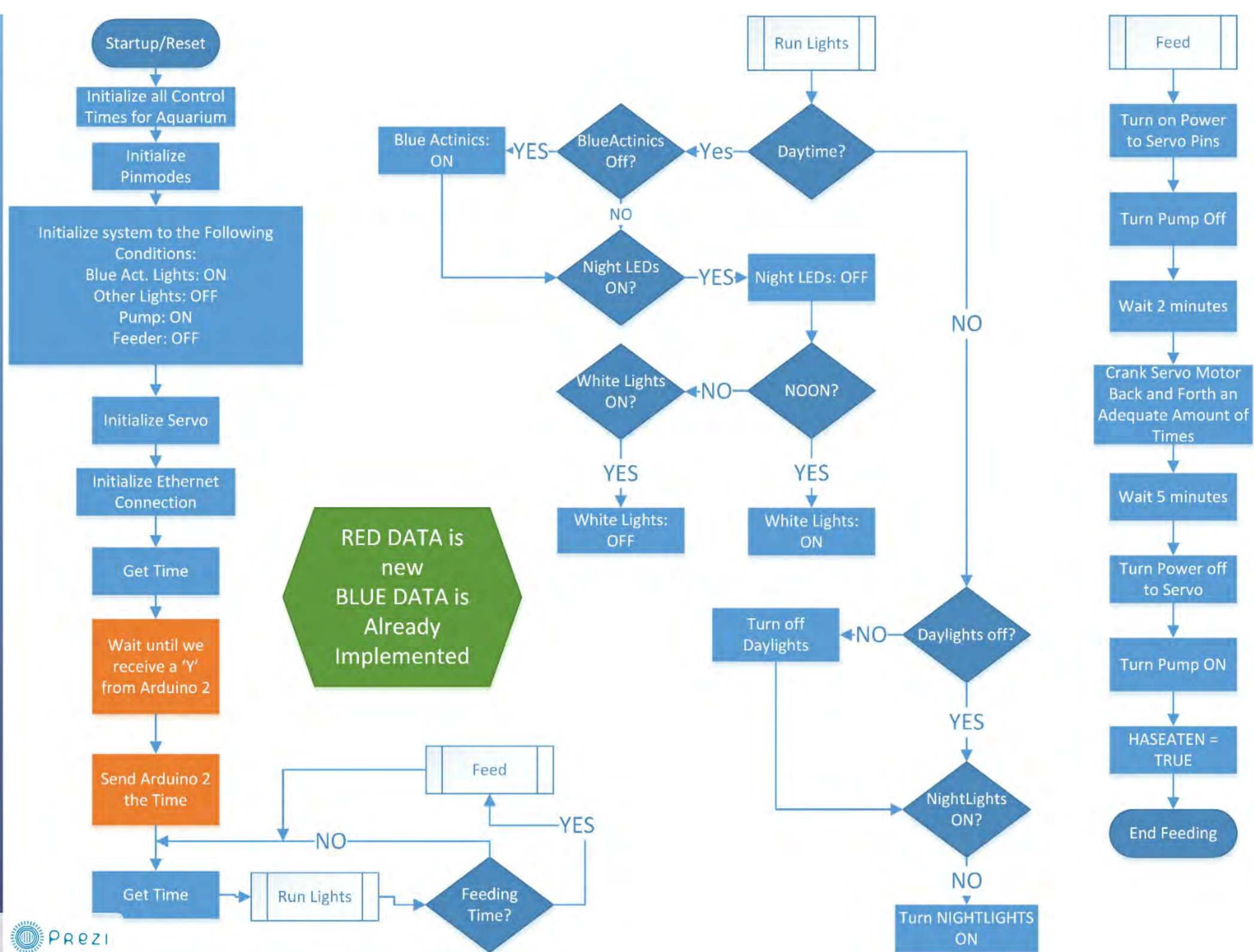
- Arduino 1
 - Controls power to components
 - Uses Ethernet Shield to get time (NTP server)
 - Sends time to Arduino 2 on Startup
- Arduino 2
 - Initialize LCD screen
 - Waits for time data from Arduino 1
 - Reads sensor data
 - Writes to LCD screen
 - Uses state machine to read sensors and update the screen every one minute

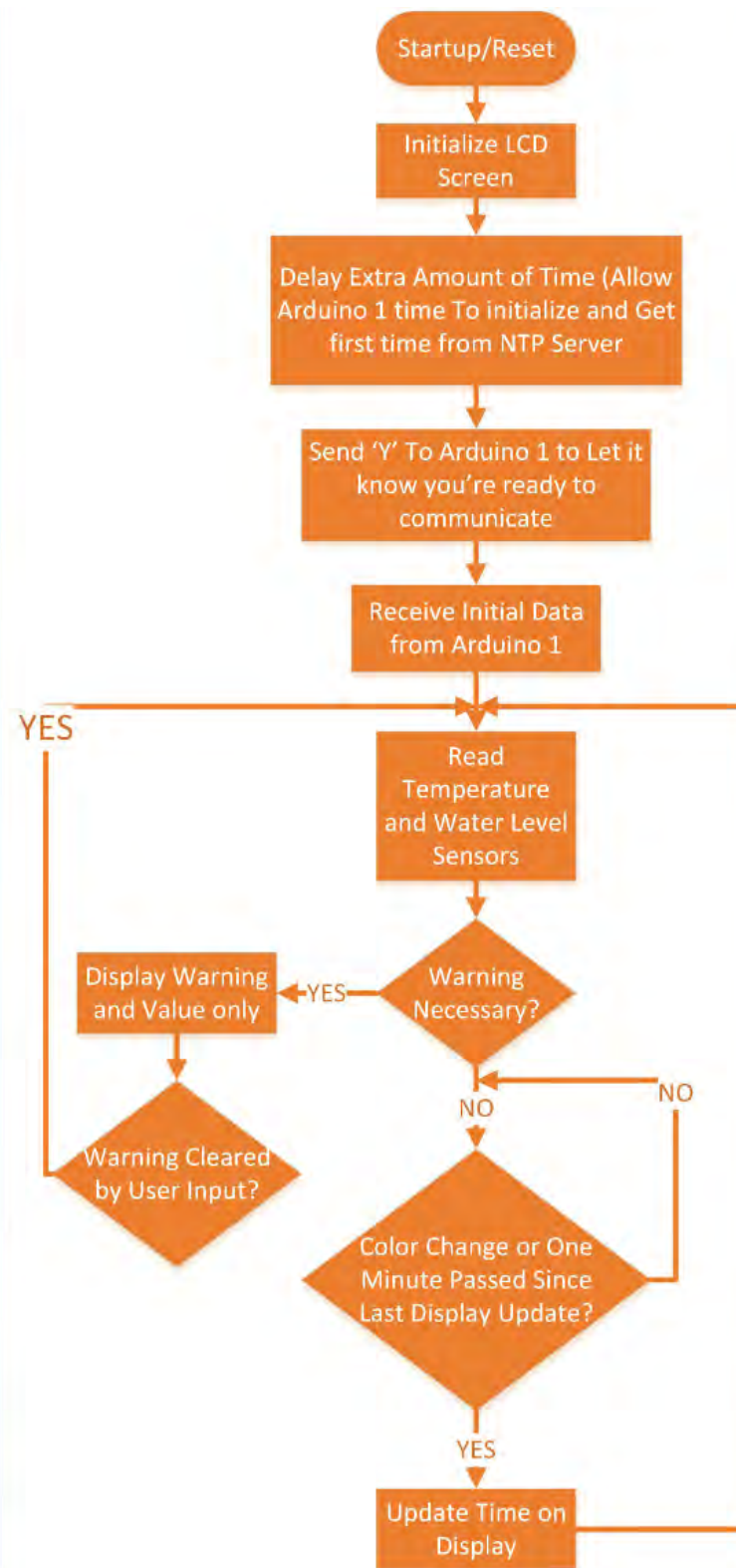
Arduino 1



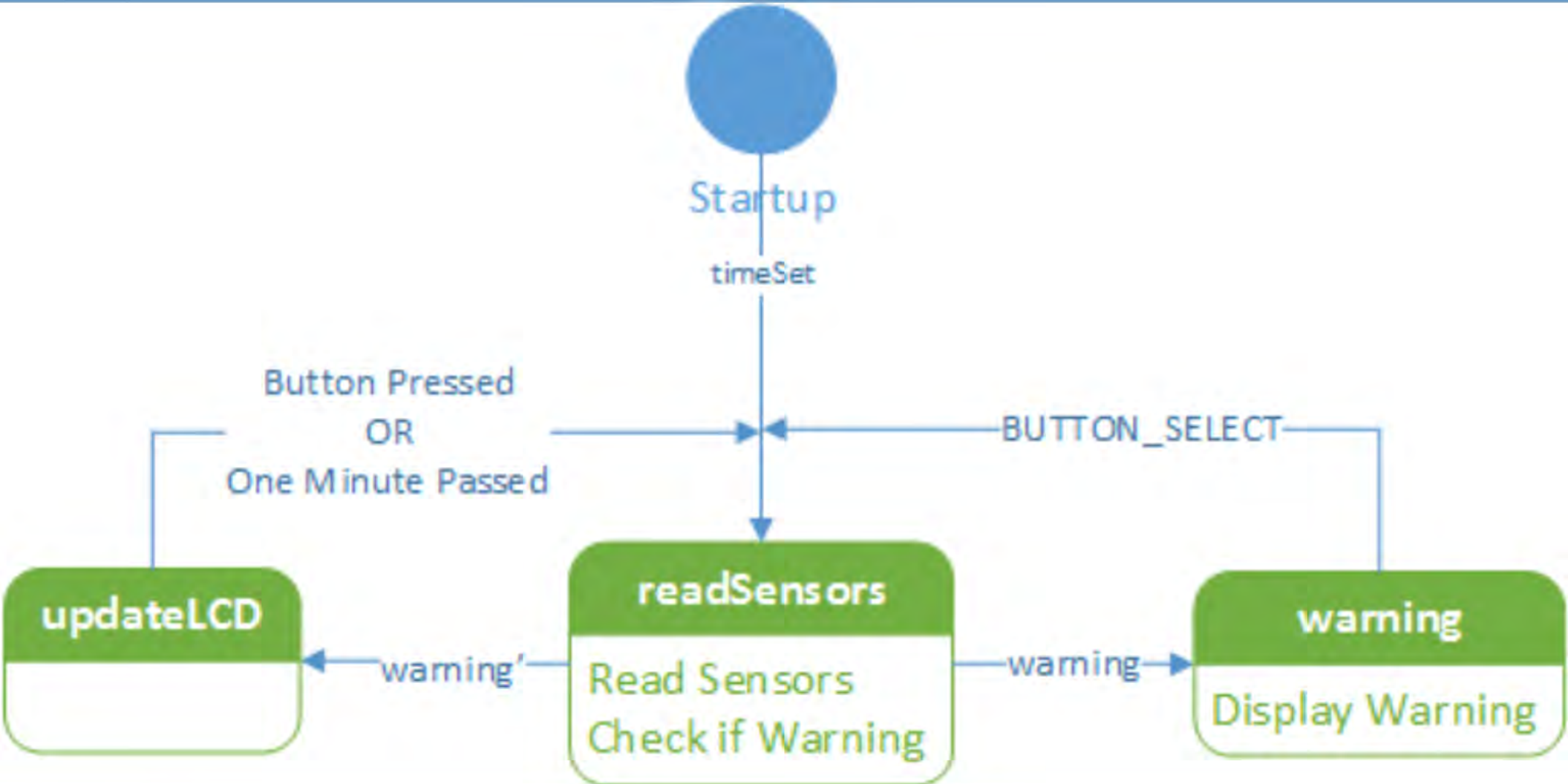
Arduino 2







State Machine



Conclusions

Arduino Libraries

- Helpful for quick high level coding
- More difficult to fine tune
 - May have to scour the header/cpp files to determine how specific functions work

Oscilloscopes can be extremely helpful in troubleshooting

Questions???