FINAL PROJECT PRESENTATION:

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FOUR CHANNEL TEMPERATURE CONTROLLER

Full Instrument

Basic Layout





DESIGN SPECIFICATIONS

Temperature Controller

- 4 Channels
- 8 amps max per channel
- Total 15 amps at ~110V
 - Designed to be upgradable to 220V
- Temperature measurement based on Resistive Thermal Devices (PT100)
- Temperature output controlled by Solid State Relays for long operational life

BLOCK DIAGRAM



WIRING DIAGRAM: RELAYS



WIRING DIAGRAM: CONTROL



SENSOR AMPLIFIER

• Temperature Range:

- -10° C 120° C
- ~14° F 248° F
- Total Range Difference:
 - 130° C or 234° F
- 8 bit resolution:
 - 256 data values
 - ~0.914 values/degree F
- 2.2V-2.75V -> ~0V-5V



BASICS OF TEMPERATURE CONTROL

PID Control

- P (Proportional)
 - Based on the current temperature difference
 - P component = current difference
- I (Integral)
 - Summation of temperature differences over time
 - I component = I component + (current difference * sample period)
- D (Derivative)
 - Based on rate of change of the temperature
 - D component = (current error previous error) * sample period
- Duty Cycle of Output = Kp * P + Ki * I + Kd * D

USER INPUT/OUTPUT

• All input based on three buttons:

- Change channel
- Temperature set point up
- Temperature set point down
- All output displayed on LCD screen (4x20):
 - One line on screen for each channel
 - Each line contains current channel temperature and current channel set point temperature

PSUEDOCODE: INPUT/OUTPUT

```
Clear RTI flag

// Button 1: Change channel

If (button1&& button_pressed = =not_pressed)

Current_channel + 1

button_pressed = pressed

If (Current_channel > 4)

Current_channel = 0

End
```

```
// Ensures each button push only results in one channel change
If (!button 1 && button_pressed = =pressed)
    button_pressed = not pressed
```

```
End
```

```
// Button 2: Increase temperature set-point
If (button 2)
Switch (current_channel)
Case 1: set_temp_1 + 1
Case 2: set_temp_2 + 1
Case 3: set_temp_3 + 1
```

```
End
```

```
// Button 3: Decrease temperature set-point
```

```
If (button 3)
```

```
Switch (current_channel)
Case 1: set_temp_1 - 1
Case 2: set_temp_2 - 1
Case 3: set_temp_3 - 1
Case 4: set_temp_4 - 1
```

Case 4: set_temp_4 + 1

```
End
```

TEMPERATURE INPUT: PSUEDOCODE

- All temperature values read from a single A/D converter
- Convert raw input (0-256) into voltage value
- Convert voltage value into current resistance value of the RTD sensor
- Use resistance value to find a temperature value from pre-generated lookup table

PID CONTROL/RELAY OUTPUT

- Inside of main function
- Timing of duty cycle is based on counter
- Set output period of ~5 sec for extended relay life
 - One relay switch per output period
 - Starts high, switches low (timing based on duty cycle)
- Duty cycle determined by PID algorithm
- PID algorithm called at the beginning of the 5 sec period when the counter is reset

PSEUDOCODE: PID CONTROL/RELAY OUTPUT

PID Control / Relay Output

While (true)

cycles_counter = 0

//For each channel, set duty cycle using P control

```
Duty_cycle = Kp * (set_temp - current_temp)
```

For each channel, if (duty > 100)

Set to 100

Turn on PT3 – PT6 for relay outputs

For each channel, if (cycles_counter > cycles_counter * duty cycle / 100)

Turn off the channel

```
cycles_counter + 1
```

End

TIMING

Temperature Output Timing

- In the main program loop Slowest timing 1/8 sec
- Set period of ~5 sec
- Controlled by duty cycle

Interrupt Loop

- Controls:
 - User Input •



CONCLUSION/PROGRESS

- Temperature controller using a PID control system
- Goal:
 - Circuit:
 - Finalize construction of the components and wiring
 - Modify amplification circuit for best resolution
 - Coding:
 - Implement a PI system (D deemed unnecessary by Rad)
- Current Progress:
 - Circuit:
 - Basic Temperature Acquisition
 - Coding:
 - Currently have implemented a system based on proportion
- Questions?